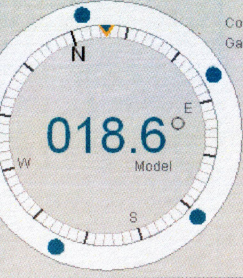
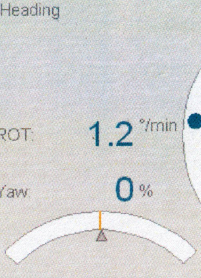
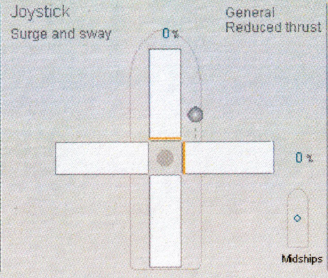


52:Operator

Measured	True
38.3	38.3
36.0	36.0
30.1	30.1
34.8	34.8



Controller Mode: **Relaxed**
Gain level: Low

NUP

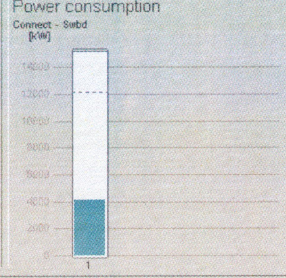
Gyro 1 2 3

Rotation center position

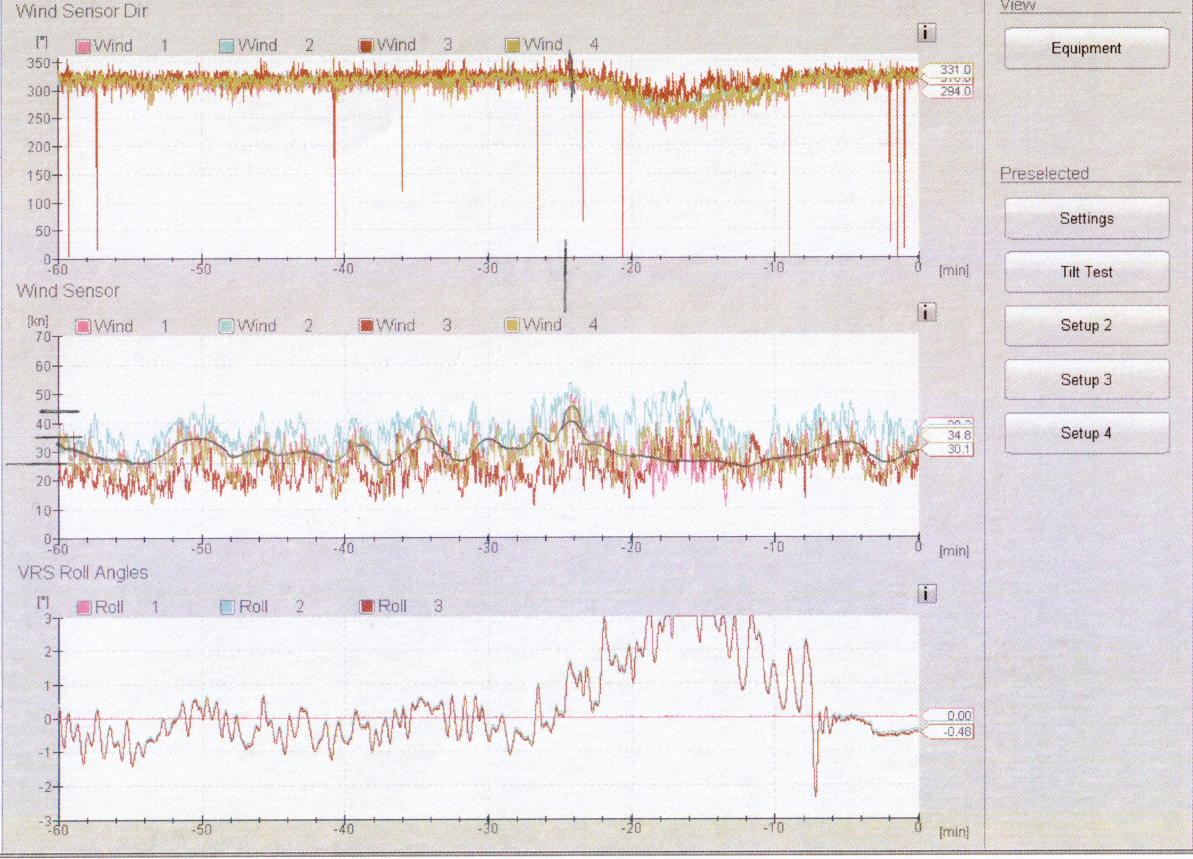
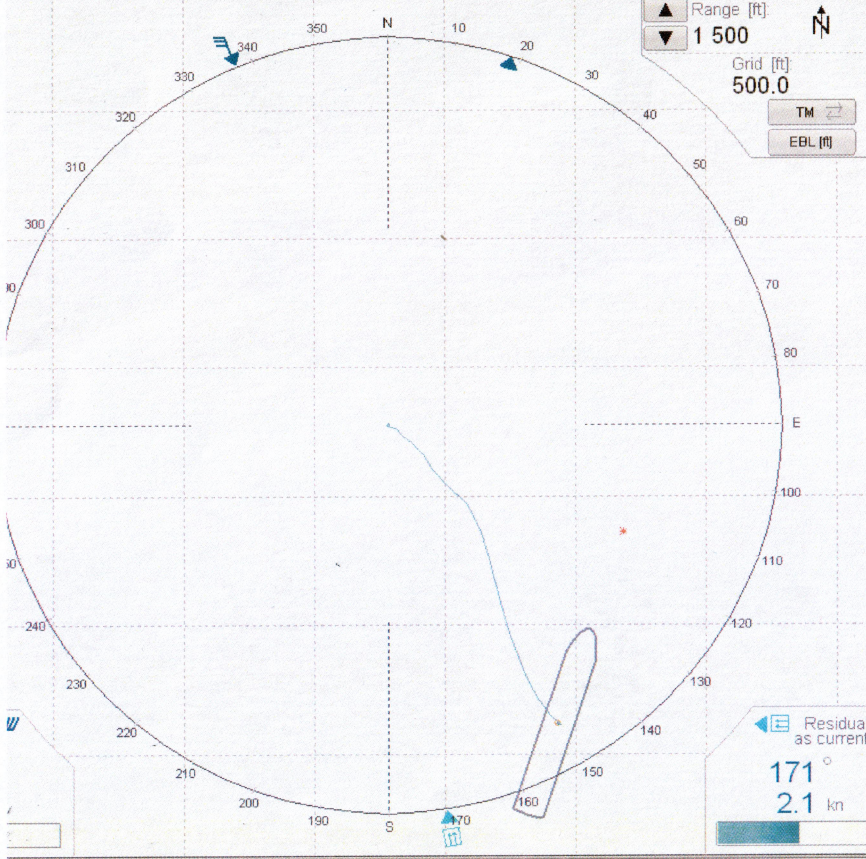
30 20.3463 N
088 30.5280 W

Reference origin sensor GPS-1

DP class None



- Palette
- Day
 - Dusk
 - Night
 - Independent



- View
- Equipment
- Preselected
- Settings
 - Tilt Test
 - Setup 2
 - Setup 3
 - Setup 4

K-POS
DP-OS1 Operator

12 Mar 22 01:10:35

JOYSTICK

A Normal

00:43:16 12 Mar 22

Gyro 1 rejected

10

Positioning Settings Sensors Thruster
Alarms View Units Section

Main: DP

A Normal

00:28:24 12 Mar 22

Misuse VRS out of limits roll

heel speed 800 0.1 kn Model

JOYSTICK
Stimule and sign

General
Reduced Thrust

Heading

ROT

0.2 °/min

Yaw

0 %

Midships

Controller Mode: Relaxed
Gain level: Low

NUP

Gyro

Rotation center position

30 20.3469 N
088 30.5322 W

Reference origin sensor: GPS-1

DP class: None

Power consumption

Current: 1000

Volt: 1000

Power: 1000

Power: 1000

Power: 1000

Power: 1000

Power: 1000

Power: 1000

Power: 1000

Power: 1000

Power: 1000

Power: 1000

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Power: 1000

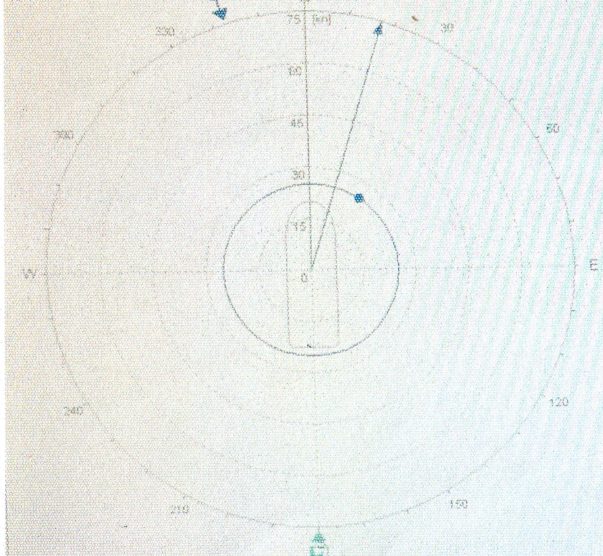
Power: 1000

Power: 1000

Power: 1000

Capability plot

No results available



Range [km] 75.0

Present wind 25.0 kn 343°

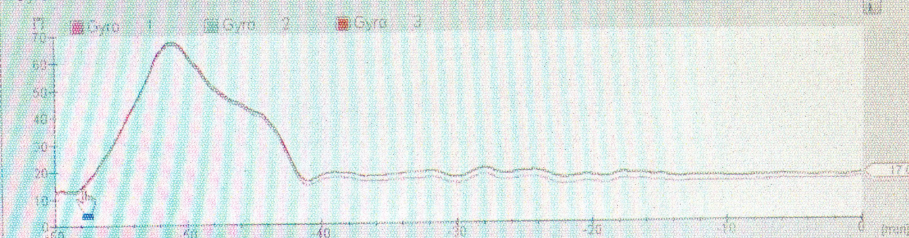
At time of analysis
Waves 0.0 ft 180.0°

Sea current 0.0 kn 180°

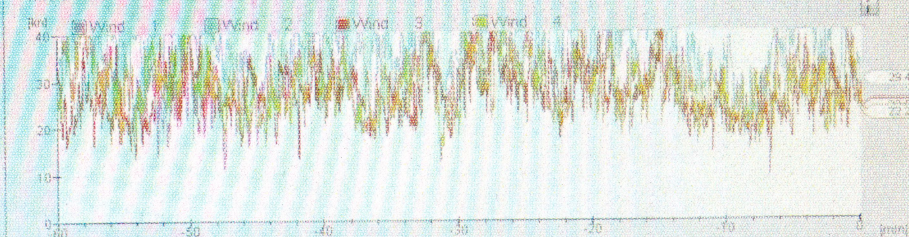
Vessel HDG

Vessel HDG: 017.0° EBL HDG: 000.0°

Gyro



Wind Sensor



VRS Roll Angles

