NATIONAL TRANSPORTATION SAFETY BOARD

Office of Aviation Safety Aviation Engineering Division Washington, DC 20594

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ADDENDUM NUMBER 2 TO THE STRUCTURES GROUP CHAIRMAN'S FACTUAL REPORT

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A. ACCIDENT

B. STRUCTURES GROUP

Chairman: Brian K Murphy National Transportation Safety Board Washington, DC

C. AIRBUS REPORT

1. "AAL587 Investigation, Accident Analysis – FEM Global model VTP & Rudder"

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1. Introduction

For the investigation of the loading conditions sustained by the vertical stabilizer during the accident of flight AAL587 a detailed 2D FEA-model has been created for the fin box, the rudder and the rudder supports.

This model is attached to the rear fuselage which is clamped far enough from the fin attachment to avoid structural interference.

The report describes the idealization of the model and the analysis performed. Results are provided for

- the design lateral gust load case BI17 for the A300-600R
- the accident loading condition W372

and

• the accident loading condition W375

in terms of strains, max. fin deformation and attachment forces.

The influence of the rear fuselage stiffness on the fin attachment loads between front, center and rear fittings has been discussed.

2. Global 2D-FE-model for vertical stabilizer and rudder structural analysis

2.1 Detailed view of the A300-600R VTP structure components

The main structure components of the vertical stabilizer are shown on figure 2.1. The fin box itself is assembled from front spar, center spar, rear spar, LHS and RHS skin panels and 18 ribs as shown on figure 2.2.

Components of the VTP

2.3 Idealization of the skin panel

The ply stacking of the skin was modeled with MAT2 material cards and PSHELL elements.

In the certification model the skin field between 2 ribs and 2 stringers was modeled with one quadrilateral element each. For the accident investigation model it was decided to remesh these areas with four elements instead of one, to achieve a more detailed strain distribution information for the skin panels. See following figures 2.6 to 2.9.

2.4 Idealization of the main attachment fittings

In the investigation model used properties for the lug are the same compared to the certification model from 1985.

Changes relative to the certification model from 1985 are as follows:

- use for the lug the CQUAD4 elements where possible
- lug plane is parallel to fin box center plane

Figure 2.10 shows the main attachment shape and figure 2.11 shows the corresponding FE-mesh of the investigation model.

2.5 Idealization of Fuselage / VTP connection in the global 2D model

The idealization of the fuselage / VTP connection bolt in the global 2D NASTRAN model was made with two RBE2 elements (rigid body element) per fuselage clevis (see figure 2.12). One 3-node RBE2-element represented the stiff bolt in the fuselage clevis. The other RBE2-element was on the one side connected with the node of the bolt RBE2-element and on the other side, but same location, with the VTP main attachment lug center point.

2.7 Rudder Hinge Line / Rudder Deflection

Each calculated load case (lateral maneuver) is defined by the load distribution of fin and rudder and the rudder deflection angle (see figure 2.15 and 2.16). All analyzed load cases were calculated with the rudder in deflected position.

2.8 Boundary Conditions of the global model

The structural model is clamped (Degree of Freedom 1-6 /translation and rotation) at the perimeter of the first frame C72 of section 18 (see figure 2.17).

3. Description of considered load cases

The loads are provided as nodal forces on both surfaces of the finite element model. The load resultants Qy, Mx and Mz are given in the global coordinate system or in the fin coordinate system which is defined by the 36.5% chordline of the vertical stabilizer. The origin of these coordinate systems is the intersection with the global system X-axis which is 85mm below the fin box main fitting center line (see figure 3.1).

The lateral force is for both systems the same, but the moment Mx and Mz have to be transformed. The relationship of the moments between these two coordinate system is given by the equations below.

 $\alpha = 37.74^{\circ}$ (see figure 3.1)

Global Coordinate System to Component Coordinate System

$$
Mz_{cs} = Mx_{gs} \cdot \sin \alpha + Mz_{gs} \cdot \cos \alpha
$$

$$
Mx_{cs} = Mx_{gs} \cdot \cos\alpha - Mz_{gs} \cdot \sin\alpha
$$

Component Coordinate System to Global Coordinate System

 $Mz_{gs} = -Mx_{cs} \cdot \sin \alpha + Mz_{cs} \cdot \cos \alpha$ $Mx_{gs} = Mx_{cs} \cdot \cos \alpha + Mz_{cs} \cdot \sin \alpha$

4. 2D global NASTRAN VTP model results

4.1 Design lateral gust load case BI17 [Limit Load]

4.1.1 Main attachment fitting forces [BI17 / Limit Load]

Table 4.1 **Load resultant at fin root** [Component System]

Table 4.2 **Main Fitting Reaction Forces**

Table 4.3 **Lateral Load Yokes Reaction Forces**

4.2 Accident loading condition W372 [Ny integration issue18– Criteria: correlated corner bending Mx/torsion]

4.2.1 Main attachment fitting forces [W372]

Table 4.4 **Load resultant at fin root** [Component System]

Table 4.5 **Main Fitting Reaction Forces**

Figure 4.4

Table 4.6 **Lateral Load Yokes Reaction Forces**

4.2.2 Hinge arm and rudder actuator forces [W372]

Rudder deflection angle $|\n\mid$ $|\n\mid$ -11,47

Table 4.7 **Actio forces at the rudder attachment fitting**

Table 4.8 **Load resultant for the rudder**

4.2.3 Rudder attachment fitting bolt forces [W372]

Bolt forces are listed in the rudder spar aligned coordinate system.

Y hinge_line $\hat{\Phi}$ LHS **I** Y X X hinge_line *Figure 4.7*

4.3. Accident loading condition W375 [Ny integration issue18– Criteria: maximum lateral acceleration Ny]

4.3.1 Main attachment fitting forces [W375]

Table 4.10 **Load resultant at fin root** [Component System]

Table 4.11 **Main Fitting Reaction Forces**

Figure 4.8

Table 4.12 **Lateral Load Yokes Reaction Forces**

4.3.2 Hinge arm and rudder actuator forces [W375]

Rudder deflection angle $\begin{bmatrix} \n\end{bmatrix}$ -11,47

Table 4.13 **Actio forces at the rudder attachment fitting**

Table 4.14 **Load resultant for the rudder**

4.3.3 Rudder attachment fitting bolt forces [W375]

Bolt forces are listed in the rudder spar aligned coordinate system.

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4.4 Influence of the rear fuselage stiffness on fin attachment loads between front, center, and rear fittings

The global force and moments distribution at the fuselage / VTP attachments depends on the stiffness distribution of both parts. A stiffness variation on the fuselage side should show the influence on the attachment force distribution (see figure 4.13). The reference model for this investigation is the original fuselage model "*Basis 1*". Based on this model a second model "*Model2*" was created with an overall fuselage stiffness increase of 10%. The third model "*Model3*" includes a 10% increased fuselage stiffness from behind the front main attachment to the aft. The last model "*Model4*" includes a 10% increased fuselage stiffness from behind the center main attachment to the aft.

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 Table 4.16

The next two diagrams 4.1 and 4.2 show the changes in the resultant main fitting forces and for the lateral load yoke between the different model assumptions.

Fres Main Fitting

5. Summary

The FEA with the last two peak loading conditions during the accident was compared with the limit load condition of the design lateral gust case. The analysis (W375 loading condition) revealed a limit load factor of 2.05 for the resultant attachment force at the RHS rear lug and the max. strain level in the skin panel relative to the design lateral gust case BI17 of the A300-600R. The variation of the fuselage stiffness (static over determined) shows for realistic stiffness changes no significant influence. The hinge line forces for load case W375 are not at a level to cause a failure of the rudder support structure.

