ATTACHMENT 2

TO

SYSTEMS GROUP CHAIRMAN'S FACTUAL REPORT

DCA17FA076

DC-9-83 (MD-83), N786TW, On Aircraft Elevator Test Plan (N787TW)

THE FOLLOWING ARE EXPERIMENTAL TEST PROCEDURES AND ARE NOT TO BE USED FOR AIRCRAFT MAINTENANCE OR FOR DETERMINING AIRCRAFT SERVICEABILITY.

 Checks with Hydraulic Power Of 	f	F		I
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A.	Dep	epressurize left hydraulic system (AMM 29-00-00/201, paragraph 8.A.).					
В.		lace horizontal stabilizer in neutral position by aligning protruding head rivets on left side orizontal stabilizer leading edge with protruding head rivet on side of vertical stabilizer.					
C. Measure and record limits of elevator surface travel.							
	(1)		e elevator surface in neutral position by aligning trailing edge of elevator with ruding head rivet on side of vertical stabilizer.				
	(2)	Place inclinometer on elevator surface and set to reading zero.					
(3) Using hand force to move elevator, measure and record elevator surface proof travel.		g hand force to move elevator, measure and record elevator surface positions at limits avel.					
		(a)	Full elevator TEU: Left Right				
		(b)	Full elevator TED: Left Right				
			(Ref. rig tolerances: 27.0 +/- 0.5 degrees TEU, 16.5 +/- 0.5 degrees TED)				
D.	Measure and record elevator control tab travel.						
	(1)	Move right control column slightly fore and aft and allow column to stabilize in neutral position.					
	(2)	Place elevator surface in neutral position by aligning trailing edge of elevator with protruding head rivet on side of vertical stabilizer.					
		NOT	E: All control tab angles are measured relative to elevator surface using 5916715 protractor.				
	(3)		sure and record TEU or TED distance of control tab from elevator surface: Right				

(Ref. rig tolerance: 0.00 +/- 0.25 degree)

		(4)	upp	d elevator surface in neutral position and move right control column forward until er stop on elevator control tab inboard ge fitting.
			(a)	Record control tab TEU position: Left Right
				(Ref. rig tolerance: 20 +/- 2 degrees)
		(5)		d elevator surface in neutral position and move right control column aft until lower stop elevator control tab crank contacts stop on elevator control tab inboard hinge fitting.
			(a)	Record control tab TED position: Left Right
				(Ref. rig tolerance: 26 +/- 2 degrees)
		(6)	Mo	ve right control column full forward and elevator surface full TED.
			(a)	Record control tab TEU position: Left Right
				(Ref. rig tolerance: 18.5 +/- 3.5 degrees)
		(7)	Mo	ve right control column full aft and elevator surface full TEU.
			(a)	Record control tab TED position: Left Right
				(Ref. rig tolerance: 26.5 +/- 2.5 degrees)
2.	Ch	ecks v	with	Hydraulic Power On
	A.			re left hydraulic system (AMM 29-00-00/201, paragraph 8.B. external pressure source or er transfer unit pressure).
	В.	Mak	ke su	re aircraft is powered electrically.
	C.	hori		re horizontal stabilizer is in neutral position (i.e., protruding head rivets on left side al stabilizer leading edge aligned with protruding head rivet on side of vertical ·).
	D.	Acti	vate	flight recorder by placing FLT RCDR switch on overhead panel to GND TEST position.
		<u>NOT</u>	S	Flight recorder can also be activated by releasing parking brake and either placing a fuel shutoff lever in on position or de-energizing ground control relays (left ground control relay C/B open, aircraft in flight mode).

NOTE: Recording clock time when check events occur will help identify events in recorder data.

E. Flight control rollout check.							
	(1)	Slov	vly move right control column full forward, full aft, and back to neutral.				
	(2)	Slov	vly move either control wheel full left, full right, and back to neutral.				
	(3)	Slov	vly move either set of rudder pedals full left, full right, and back to neutral.				
F.	Che	Check elevator boost actuation point.					
	(1)		vly move right control column forward and stop when blue ELEVATOR POWER ON light DAP illuminates.				
	(2)	Retu	urn control column to neutral.				
G.	Obs	erve	elevator surface motion and travel during boost system actuation.				
	(1)		tion personnel and/or video camera(s) and observe and record elevator surface avior during boost system actuation.				
		(a)	Make visual note during next step of apparent speed of surface when movement occurs and force of contact with limit stops for comparison with test done in paragraph 3.D.				
	(2)	Mov	ve right control column full forward and hold to actuate boost system.				
	(3)		ord elevator surface TED position while boost system is actuated: Right				
	(4)	Retu	urn control column to neutral.				
Н.	Check elevator boost system operation with control columns in neutral position.						
	(1)	Dete	ermine elevator control tab position when boost system actuates.				
		(a)	Make sure control columns are in neutral position.				
		(b)	Place elevator surfaces at approximately neutral position.				
		(c)	Move right elevator surface TEU until travel limit stop contacts.				
		(d)	Place 5916715 protractor on left elevator surface to measure control tab angle.				
			NOTE: Boost system will move both elevators. Be prepared to read control tab				

position measurement at point where movement begins.

(e) Slowly move left elevator surface TEU and stop when boost system just begins to

move right elevator surface TED.

	(1)	just began to move:				
	(g)	Place elevator surfaces at approximately neutral position.				
	(h)	Move left elevator surface TEU until travel limit stop contacts.				
	(i)	Place 5916715 protractor on right elevator surface to measure control tab angle.				
		NOTE: Boost system will move both elevators. Be prepared to read control tab position measurement at point where movement begins.				
	(j)	Slowly move right elevator surface TEU and stop when boost system just begins to move left elevator surface TED.				
	(k)	Record TEU position of right control tab that was measured when left elevator surface just began to move:				
(2)	Mea	asure and record control tab position with elevator surface full TEU.				
	(a)	Depressurize left hydraulic system (AMM 29-00-00/201, paragraph 8.A.).				
	(b)	Make sure control columns are in neutral position.				
	(c)	Move elevator surfaces TEU until travel limit stops contact.				
	(d)	Record control tab TEU positions using measurements taken with 5916715 protractor Left Right				
(3)	surf	ontrol tab TEU measurements recorded when boost system just began to move elevator faces (steps 2.H.(1)(f) and 2.H.(1)(k)) are <u>larger</u> than measurements recorded with vator surfaces at full TEU position (step 2.H.(2)), do following steps:				
	(a)	Make sure control columns are in neutral position.				
	(b)	Move elevator surfaces TEU until travel limit stops contact.				
	(c)	Using multiple hands to evenly distribute force on each control tab trailing edge, push trailing edges of both tabs upward at same time and attempt to move tabs to approximately positions recorded when boost system just began to move elevator surfaces (steps 2.H.(1)(f) and 2.H.(1)(k)).				
	(d)	Record whether tab movement was possible and whether it was possible to reach attempted positions:				
		NOTE: Previous steps are intended to help assess likelihood of wind force being able to deflect control tabs against load feel spring.				

- (4) If control tab TEU measurements recorded when boost system just began to move elevator surfaces (steps 2.H.(1)(f) and 2.H.(1)(k)) are <u>smaller</u> than measurements recorded with elevator surfaces at full TEU position (step 2.H.(2)), do following steps:
 - (a) Make sure control columns are in neutral position.
 - (b) Move elevator surfaces TEU until travel limit stops contact.
 - (c) Using multiple hands to evenly distribute force on each control tab trailing edge, push trailing edges of both tabs upward at same time and attempt to move tabs.
 - (d) Record whether tab movement was possible: _____

NOTE: Previous steps are intended to help assess likelihood of wind force being able to deflect control tabs against load feel spring.

I. Deactivate data recorder by reversing activation method used in step 2.D.

3. Checks Using Elevator Accumulator Pressure

- A. Make sure horizontal stabilizer is in neutral position (i.e., protruding head rivets on left side horizontal stabilizer leading edge aligned with protruding head rivet on side of vertical stabilizer).
- B. Check accumulator charge and system pressure holding capability per AMM criteria (ref. AMM 27-30-11/201, par. 6.).
 - (1) Depressurize left hydraulic system (AMM 29-00-00/201, paragraph 8.A.).
 - (2) Make sure elevator hydraulic system is depressurized by opening elevator system bypass valve located aft of accumulator pressure gauge or by cycling control column several times.
 - (3) Make sure accumulator pressure gauge reads 2000 +/- 50 PSI.
 - (4) Make sure accumulator pressure does not drop more than 100 PSI in 30 minutes.
 - (5) Close elevator system bypass valve.
 - (6) Hold elevator surfaces at approximately neutral position.
 - (7) Pressurize left hydraulic system (AMM 29-00-00/201, paragraph 8.B. external pressure source or 8.E. power transfer unit pressure).
 - (8) Allow system to stabilize for 3 to 5 minutes and make sure that accumulator pressure gauge reads system pressure (3000 PSI).

	(9)	Sh	ut off hydraulic pressure source.				
	(10)		low system to stabilize for 10 minutes and make sure that stabilized pressure reading on cumulator pressure gauge is not less than 2200 PSI.				
	(11)	Re	ecord stabilized pressure:				
	(12)		ecord pressure after 10 minutes: Pressure shall not be less than 2200 PSI ter 10 minutes.				
C.	Check accumulator system pressure holding capability after extended period without powered hydraulic pressure source.						
	(1)	Holo	l elevator surfaces at approximately neutral position.				
	(2) Pressurize left hydraulic system (AMM 29-00-00/201, paragraph 8.B. external pressure source or 8.E. power transfer unit pressure) and allow system to stabilizer for 3 to 5 minutes.						
	(3)	(3) Shut off hydraulic pressure source.					
	(4) Allow system to stabilize for 10 minutes and record stabilized pressure reading on accumulator pressure gauge:						
	(5) I	Reco	ord reading on accumulator pressure gauge after hours:				
	<u>!</u>	NOT	E: Do paragraph 3.D. check as soon as possible after recording pressure reading.				
D.	Chec		post system operation after extended period without powered hydraulic pressure				
			tion personnel and/or video camera(s) and observe and record elevator surface avior during boost system actuation.				
	((a)	Make visual note during step 3.D.(2) of apparent speed of surface when movement occurs and force of contact with limit stops for comparison with test done in paragraph 2.G.				
	((b)	Record any differences observed:				
	(2)	Мо	ve right control column full forward and hold to actuate boost system.				
	(3)		cord elevator surface TED position while boost system is actuated: t Right				
	(4)	(4) Return control column to neutral.					