#### APPENDIX C

Boeing Presentation on Simulator Methods and Limitations March 2000

# EgyptAir Flight 990 Accident Investigation Simulation of FDR Data with Split Elevators + Data Derived from Radar Boeing Airplane Simulation Lab (ASL) March 30-31, 2000

- Introduction and Agenda
- Simulations:

1

- Background Simulations
- Backdrive Simulations on the 767E- Cab With and Without Pilot Interaction
  - Human Performance Synchronized CVR/FDR Closed Sessions
  - Human Performance Open Sessions
  - Performance and Operations Group Sessions
- Important Details of these 767E- Cab Simulation Sessions
- Limitations of the 767E- Cab Simulations
- Additional Items of Note

### **Background Simulations**

- Purpose:
  - Determine the control inputs required to drive the event
    - Develop a match of the FDR data through the elevator split plus the radar data (through climb to 24,000 feet)
    - Validate an adjusted aerodynamic database
- Run on engineering workstation no cab or pilot in the loop
- Simulation initially trimmed at 33,000 feet, Mach = .79, Gross Weight = 390,000 pounds, and CG = 23.3% mac.

### **Background Simulations (continued)**

- Simulation Longitudinal
  - For FDR time 1235 to 1265 (Mach = .91) the control column with equal left and right elevator angles is driven to match the FDR pitch angle.
  - For FDR time 1265 to 1290 (end of FDR data) the simulation is driven by the FDR left and right elevator angles including the split. A small increment in pitching moment coefficient is applied above Mach = .91 to retain a good match with the FDR pitch angle. The flight path angle and normal load factor show good agreement through out the FDR data.
  - Beyond FDR time 1290 the control column (equal left and right elevator angles) is driven to match the pitch angle derived from radar data.
- Simulation Lateral/Directional
  - For FDR time 1235 to 1290 (end of FDR data) the wheel and rudder pedals are driven to match FDR roll and heading angles.
  - Beyond FDR time 1290 the wheel and rudder pedals are driven to match the roll and heading angles derived from radar data.

## **Background Simulations: General Information**

- For FDR time 1235 to 1290:
  - Throttle starts at the initial simulator trim point. Its movement to idle and the fuel cut are based on FDR timing.
  - Speedbrake handle is driven by FDR data.
  - Stabilizer position follows the FDR data from the initial simulator trim point.
- Beyond FDR time 1290:
  - Engines are assumed to be shut down.
  - Three hydraulic systems and the primary flight controls remain functional until the airspeed decreases below 110 knots.
  - Speedbrake handle remains deployed.
  - Stabilizer position remains constant holding the last FDR value.

## Backdrive "Split Elevator" Simulations (Simulator Scenarios 1 & 2)

- Purpose:
  - Provide a replay of the flight deck instruments and controls during the event with and without the CVR (*No pilot interaction*).
  - Experience the timing of events, control force levels with split elevators, and sounds on the flight deck.
- Flight deck controls driven with FDR data.
  - Throttles
  - Speedbrakes
  - Engine cut logic
- Flight deck controls driven with data derived from the Background Simulation.
  - Control wheel
  - Rudder pedals
  - Right control column (Scenario 1) or Left control column (Scenario 2)

5

## Backdrive "Split Elevator" Simulations with Pilot Interaction (Simulator Scenarios 3 & 4)

- Purpose:
  - Allow the pilot to take control of the aircraft during the elevator split and experience the workload and control forces required. The pilot is able to control the column, wheel, and stabilizer. To achieve this interaction the pilot must apply a column force that exceeds 20 pounds.
- Elevator Split Cues:
  - Approximately FDR time 1275 seconds
  - Indication of Engine Cut
- Scenario 3: The pilot flying pulls left column
- Scenario 4: The pilot flying pushes right column

## **Important Details of these 767E- Cab Simulation Sessions**

- The cab area contains a mockup of the aft bulkhead of the flight deck including the entry door, adjoining lavatory, and the passage way between them. Two jump seats are also located at the rear of the flight deck.
- Data will be recorded and a time history of each run will be kept.
- The backdrive simulations (all 4 Scenarios) continue through the climb to an altitude of 24,000 feet.
- The simulation beyond the climb to 24,000 feet has not been verified.
- The backdrive simulations with pilot interaction (Scenarios 3 and 4) are designed for the pilot to take control during the elevator split.
- Aerodynamic database extended from Mach = .91 to Mach = .98.
- Computer generated instruments are displayed on the windscreen (elapsed and FDR time, normal load factor, engine off lights, left and right elevator angles, left and right computed column forces, and the column force for the pilot flying).

### **Important Details of these 767E- Cab Simulation Sessions (continued)**

- For FDR time 1235 to 1265 the left and right computed column forces are based on an average of the recorded left and right FDR elevator angles. For FDR time 1265 to 1290 they are based on their respective FDR elevator angles.
- The simulation backdrive may be started at any arbitrary time between FDR time 1235 and 1330.

# **Limitations of the 767E- Cab Simulations**

- The cab is fixed base. Motion is not available.
- The visual landscape is featureless land with a visible horizon.
- No Mach or stall buffet is modeled.
- Certain status messages are displayed erroneously on EICAS.
- No metric displays for fuel quantity and fuel flow.
- No thrust reverser isolation lights.
- No stand-by compass.
- The mode control panel is different than the EgyptAir configuration (no Control Wheel Steering).
- Wind and engine noise are not modeled.
- Single control loader. Control columns move symmetrically.

# Limitations of the 767E- Cab Simulations (continued)

- No hydraulic decay model or elevator blowdown model that simulates the loss of hydraulic pressure and maximum elevator capability as airspeed decreases with windmilling engines.
- The asymmetry and un-steady aerodynamics of stalls are not accurately represented.
- The low oil pressure light does not illuminate, nor does the caution alert (beeper) function during the low oil operation noted on the FDR.
- The auto-throttle rate of the cab throttle handles is limited to the autopilot rate (around 10 degrees/second), but the engine parameters respond to FDR throttle and fuel cut timing.
- Prior to starting the simulation the speedbrakes must be armed manually.

# Additional Items of Note

- A "chase-plane view" of the airplane and a duplication of the windscreen display will be presented on separate monitors in the cab area.
- The FDR airspeed and altitude are derived from the airplane's Air Data Computer (ADC). The calibration of the ADC has not been verified for speeds above MD/VD (.91/420 knots).
- Electrical stabilizer trim using the pickle switches on the wheel is not available after the fuel cuts.
- The column cut-out switches do not inhibit stabilizer trim when the columns are split (one forward and the other aft).
- Please keep hands and feet free of simulator controls prior to re-initialization ("IC")

									<b>—</b> —										1								
П	} ₽	A R		PRES	301 SURE	000	<b>r</b>		<u> </u>					ee.			· ·	<b>500</b>		DAD							
	-		~ 1	(FEE	r) 251	00.	<b> </b> [ι	ONG	ITU	DIN	AL A	XIS							<u> </u>								
		161	r_piot		201	00.		ONLY AILER	CM TR	IM TI	ERM A POILE	RS DF	E RIVEN			<u>```</u>											
		÷	176			500.	-	BY MA	TH PI	LOT N - FDR	WHEEL					L	~							ļ			
			2 2MARO	COMP	UTED PEED	00				- RAD - Sin		ION			حتشتة				+								
$\left  \right $	+	+		(KNO	TS)																••••						
			DISKA																				••••				
H	╡	╈	Ŋ																<b>†</b> •••								
	+		[mi	NUMB	ER	.8.		<b>-</b>	+									-	1		••••						
			EGYP1	<u></u>		.7	<b>-</b>												1			•••					
E	1		AIR.	N 1		100.	F			-				RIGH	1	٨						· · · ·					
			767 -	( <b>%</b> )	<u> </u>	50.					and a second				<u> /</u>	ΗŤ								à			
		57	300 /			1			CENT	ER						<u> </u>							N. C. C. L.			···	
20		INAL		AUTO	PILOT																/	<b>_</b>			~~~~	•	
MP			ENT (			0	· · · · ·																	:			
NY		N UA	31 0	ATTI	H TUDE	20.												$\square$			:						
		>	99 1	1020		40.		F . DOV									<b>[</b>						· ·				
-	2		_	VANE	ANGL	<b>F</b> 10.	NUS						· .	1			<u>س</u> ند										
	Óff I.	N.	767.	OF A (DEG	TTACK REES)	-20					$\sim$		<u> </u>							2 2			• • • •				
	ľ	5	300			0	NOS	E DOV	N.																ч. Т.		
				FLIG	HT	20		-			C. Ser			· · ·													
				PATH (DEG	ANGL REES )	Ē							-								C			& GR		SPEED	A04.)
					:	100.	NOS	E DOV	N							,					S	MULA	TION		-		<u></u>
				COLU	MN	0		1																•		••••	
				(LBS	<b>)</b>	10.0						···			~~~~	17-	RIG	Ţ						cl cn	trm trm		05
				CONT	ROI	10								<b>1</b>		- <b>X</b>	ñ.,/	2						- <u> </u>	trm		. 0
				COLU (DEG	MN REES)	5									-	1	/	FT									0
							NOS	E DOV							1	<u></u>		~~~	<u></u>				· • - • • •				
				1914 - 19		5				••••••••••••••••••••••••••••••••••••••				2==*	-			RIGHI									
				ELEV	ATOR	0		-		-				LEFT		$\bigtriangleup$	$\square$	$\sum$					• • • • •		\	_	
				DEFL (DEG	REES	)N  -5				)Ť		-13		RIGH			$\sim$	$\sim$		$\langle \rangle$						<u> </u>	
						4	NOS	E DOV	<b>N</b> N						-							 :>					
				STAB		R	[						~			-											
				(UNI	TS)		NOS	E DO	MN .										,								
			Ì			2.	1									$\gamma$	بمنبر	V.					••••				
				LOAD	FACT	1. OR				J.					للحثنع									****			
					<b>,</b>	0				<u> </u>	<u>~</u>		~	-						<u></u>							
				SPEE	BRAK	E 1.		· .		<u> </u>							DEPL	OYED									
				HAND	LE EDIAH	En.	÷ .			1.1	1. A.	1 .			•			. 1						1	1 1 1 A		
				HAND	EPLOY	ED)										<u> </u>						<u> </u>					
				HAND (1=D STIC	EPLOY K	ED) 0										y							S1	іск з	HAKE	ار ۲	
				HAND (1=D STIC SHAK (-1=	EPLOY C ER ACTIV	ED) 0 E) -1.																	\$1	ICK S	HAKE	8	

•				1	112.1	1				_	+			1	Τ												
15	12			PRES	30 SUBE	00	+	+					<u> </u>		+	<u> </u>										<u> </u>	
Ť	ĬĬ	Ř	6	ALTI	TUDE	000	L		FRAI	ΔΥ	15	<u> </u>	<u> </u>	1				FDR	R	ADAR							
		2	Ē					ONLY	CM T	RIM T	ERM /		E						<b> </b>					بيبيل			•
		RENZE	Ē	: 	20		╉┤	AILEI BY M	RONS . Ath P	AND S	WHEEL	RS DI	RIVEN		:		÷::	1						• • • • •	+		
			22			\$00.	+			- FDI				<u> </u>					<b>  </b> -	*****				-			
			MAR	AIRS	PEED	400				- 511	MULAT	ION	+			-			<b>1</b>	••••			:	:			
	┿		7	(KNO	15)		1. 1. 1. 1. 1.							- And a second	1												
			VISED			144																	•••				
+	+	$\left  -\right $			<u>l sa i</u> Li en	9	†	-		-				+••*				+	<b>k.</b> ,			·		1.	+		
					F D	. 8	<u> </u>						1				·			<u>}.</u>			· .				
		- 2				.7																					
		171	Š.																								
로	5	유 ~				100.	<b>†</b>		+		-			RIGH	1	۸ I								· .	<u> </u>		
	TERA	RAD		N1	• • • •	50	-				200					Ħ											
Ĕ	ē	.R . 00	30			0			<u> </u>		· ·					ļ	4								+	•	-
ā	RECT	s a	3						CENT	ER														· .			
Ş	IONA	(ULA)		AUTO	PILOI										 	1			V							••••	
IPA	L AX	9 2 2	╏		<u>te de la</u>	0									· ['	<u> </u>	+										
R	SI		$\frac{1}{3}$		<u></u>	20.		<u> </u>		<u> </u>			<u>                                      </u>		<b> </b>	<u> </u>		<u> </u>							<u>                                      </u>	<u> </u>	
		<u>د</u> م وو		ROLL		0									5												
			1	ATTI (DEG	TUDE REES)											$\vdash$		1		$\geq$				÷			
AGE	4	76				20	RIC	энт									1						~				
	n212	7-300	-	ONT		-20				<u>.</u>													1	X		مععما	-
			M	HEE	EFEL	0				10.00	hor									0					بغيره		
				DEG	ieea)	20.									1. 1.		r si pri	a series	įγ.								
							RIC	HT																			
			-			-20.			-			LEFT				<u> </u>							1	. 7			
			H	NBO	ARD -	10.						RIGH	I		<u>i k</u> y		1	-73						$\lambda i$			<u> </u>
			(	DEG	REES	0		<b>D</b> 177								Ŋ,	Ļ.	k ۲			,					<u>.</u>	
						-20	Τ.Ε	. DO	ŴN						$\mathbb{N}$		N/		1.	ľ					معجوج	1	
			C	оптв	DARD							LEFT															
			f	DEG	REES	-10									-		-~	1.1					37				
			-	•		0								<u> </u>										~	<u>}</u>		
						- 1																					
				ATE	RAL	^		<b>L</b>	Louis										1								
			1	CCEL	ERAT	ION		[		<b>%</b>				~***		- 1:01	non	Ą.M	ľ	<b>**</b> *		•••••					
						1.	RIC	HT																			
			$\left  \right $			80.													<b> </b>								
			Ц	DEG	REES	90.													1		<u>```</u>						
						_?	RIC	HT									. <sup>.</sup>					1					
																			1				1				
			P	OS I	R	0	Ê		++++++				<u>,</u>		<u>,,,,</u>			2					Ň				
				DEG	REES)	2		 															•••••	.)./	·^,		
			s	PEED	BRAK	E 1	<b>R</b> I (	GHT									DEPL	OYED									
			1	AND 1=DE	E PLOY	ED)																					
			F			0			<u> </u>					-								. :					-
			S S	TICK	R	0			+														ST	ICK	HAKE	R I	
			1	-1=A	CTIV	E) -1.	<u></u>	<u> </u>	ļ		<u> </u>								·				•		<u>ل</u>		<u> </u>
						12	80.	12	ŧ0.	12	50.	12	50.	12	70. Tir	12 1E (S	BO. Econd	129 (S)	0.	13	0.	13	0.	13	20.	13	30.

:



